

Part 2 of Grassmannian Integrals:

Grassmannian for scattering amplitudes in 4d $\mathcal{N} = 4$ SYM and 3d ABJM
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Review from Last Time

For n -particle $N^k\text{MHV}$ amplitudes in 4d planar $\mathcal{N} = 4$ SYM there are three formulations of the kinematic data:

twistor space		momentum space		momentum twistor space
$\mathcal{W}_i = (\tilde{\mu}_i, \tilde{\lambda}_i \tilde{\eta}_i)$	$\longleftrightarrow$	$(\lambda_i, \tilde{\lambda}_i \tilde{\eta}_i)$	$\longleftrightarrow$	$\mathcal{Z}_i = (\lambda_i, \mu_i \eta_i)$
	Fourier transform eq (2.6)		incidence relations eq (2.10)	

One important thing is that whereas the first two (twistor and momentum) spaces have corresponding Grassmannians $Gr(k+2, n)$, momentum twistor space corresponds to the Grassmannian $Gr(k, n)$ of 2 dimensions less (we saw this happens because the amplitude has the MHV amplitude factored out).

Review: Important formulas from last time

Momentum Conservation: $\sum_{i=1}^n |i\rangle [i] = 0$

Plucker/Schouten: $\langle x, y \rangle |z\rangle + \langle z, x \rangle |y\rangle + \langle y, z \rangle |x\rangle = 0$. Note: these are all 2D vectors. Short Exercise: Prove.

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One answer: Since three 2D vectors must be linearly dependent, we can write: $a|z\rangle + b|y\rangle + c|x\rangle = 0$.

If we contract with $\langle z|$, we get: $a\langle zz\rangle + b\langle zy\rangle + c\langle zx\rangle = 0$, so $b = -\frac{\langle zx\rangle}{\langle zy\rangle}c$.

If we contract with $\langle y|$, we get: $a\langle yz\rangle + b\langle yy\rangle + c\langle yx\rangle = 0$, so $a = -\frac{\langle yx\rangle}{\langle yz\rangle}c$.

Thus, $0 = a|z\rangle + b|y\rangle + c|x\rangle = -\frac{\langle yx\rangle}{\langle yz\rangle}c|z\rangle - \frac{\langle zx\rangle}{\langle zy\rangle}c|y\rangle + c|x\rangle$.

Multiplying everything by $\frac{\langle yz\rangle}{c}$, we get: $0 = -\langle yx\rangle|z\rangle + \langle zx\rangle|y\rangle + \langle yz\rangle|x\rangle$

Dual space is defined by the relation: $p_i^\mu = y_i^\mu - y_{i+1}^\mu$

Then we get the momentum twistors $Z_i^! = (|i\rangle, [\mu_i])$ defined by

$$[\mu_i]^a := \langle i|_{\dot{a}} y_i^{\dot{a}a} = \langle i|_{\dot{a}} y_{i+1}^{\dot{a}a}$$

Correction/Exercise

Last time, we saw that a point Z_i' corresponds to a null-line in y -space (the null line passing through y_i and y_{i+1}), and conversely, a line in Z -space determines a point in y -space. We proved this via the formula:

$$y_i^{\dot{a}a} = \frac{|i\rangle^{\dot{a}} [\mu_{i-1}|^a - |i-1\rangle^{\dot{a}} [\mu_i|^a]}{\langle i-1, i \rangle}.$$

The proof of this formula was:

$$|i\rangle^{\dot{b}} [\mu_{i-1}|^a - |i-1\rangle^{\dot{b}} [\mu_i|^a] = \left(|i\rangle^{\dot{b}} \langle i-1|_{\dot{a}} - |i-1\rangle^{\dot{b}} \langle i|_{\dot{a}} \right) y_i^{\dot{a}a} = \langle i-1, i \rangle y_i^{\dot{b}a}$$

I incorrectly said that this formula had an error. Exercise: show that the last equality in this proof is correct.

Correction/Exercise

Answer: The key thing is to be very careful with signs and raising/lowering via the epsilon symbol (in particular, which index on the epsilon symbol matters).
For this, the main formulas are:

$$\epsilon^{ab} = \epsilon^{\dot{a}\dot{b}} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = -\epsilon_{ab} = -\epsilon_{\dot{a}\dot{b}}, \text{ which gives us:}$$

$$|p\rangle^{\dot{a}} = \epsilon^{\dot{a}\dot{b}} \langle p|_{\dot{b}} \text{ and } \langle p|_{\dot{a}} = \epsilon_{\dot{a}\dot{b}} |p\rangle^{\dot{b}}.$$

We first rewrite everything in kets. On the right:

$$\langle i-1, i \rangle y_i^{\dot{b}\dot{a}} = \langle i-1|_{\dot{a}} |i\rangle^{\dot{a}} y_i^{\dot{b}\dot{a}} = \epsilon_{\dot{a}\dot{c}} |i-1\rangle^{\dot{c}} |i\rangle^{\dot{a}} y_i^{\dot{b}\dot{a}}$$

On the left:

$$\left(|i\rangle^{\dot{b}} \langle i-1|_{\dot{a}} - |i-1\rangle^{\dot{b}} \langle i|_{\dot{a}} \right) y_i^{\dot{a}\dot{a}} = \epsilon_{\dot{a}\dot{c}} \left(|i\rangle^{\dot{b}} |i-1\rangle^{\dot{c}} - |i-1\rangle^{\dot{b}} |i\rangle^{\dot{c}} \right) y_i^{\dot{a}\dot{a}}.$$

Now, if $\dot{b} = \dot{c}$, then the expression is zero. So let's consider the cases of $\dot{b}$.

If $\dot{b} = 1$, then $\dot{c} = 2$, but then this implies that $\dot{a} = 1$ in $\epsilon_{\dot{a}\dot{c}}$;

in other words: $\dot{b} = 1 \Rightarrow \dot{a} = 1$, and similarly we can show $\dot{b} = 2 \Rightarrow \dot{a} = 2$.

In the former case, we have $\epsilon_{\dot{a}\dot{c}} = \epsilon_{1\dot{2}} = -1$, while in the latter, $\epsilon_{\dot{a}\dot{c}} = \epsilon_{2\dot{1}} = -1$. Therefore, in both cases, we have $\epsilon_{\dot{a}\dot{c}} \left(|i\rangle^{\dot{b}} |i-1\rangle^{\dot{c}} - |i-1\rangle^{\dot{b}} |i\rangle^{\dot{c}} \right) = \left(|i\rangle^2 |i-1\rangle^1 - |i-1\rangle^2 |i\rangle^1 \right) = \langle i-1, i \rangle$, while $\dot{a} = \dot{b}$. Thus the statement is proved.

Exercise

Finally, we saw that using the formula for y above, we could prove the formula for going directly from momentum twistors back to momentum space:

$$[i] = \frac{\langle i+1, i \rangle [\mu_{i-1}] + \langle i, i-1 \rangle [\mu_{i+1}] + \langle i-1, i+1 \rangle [\mu_i]}{\langle i-1, i \rangle \langle i, i+1 \rangle}.$$

Exercise: Suppose we want to write this as a matrix transformation from $[\mu]$ to $[i]$. Write the matrix for the case of $n = 4$.

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Exercise: Suppose we want to write this as a matrix transformation from $[\mu]$ to $[i]$. Write the matrix for the case of $n = 4$.

Hint: $[2] = \frac{\langle 3,2 \rangle [\mu_1] + \langle 2,1 \rangle [\mu_3] + \langle 1,3 \rangle [\mu_2]}{\langle 1,2 \rangle \langle 2,3 \rangle}$, and shift everything by one for each row.

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Answer:

$$\begin{pmatrix} [1] \\ [2] \\ [3] \\ [4] \end{pmatrix} = \begin{pmatrix} \frac{\langle 4,2 \rangle}{\langle 4,1 \rangle \langle 1,2 \rangle} & -\frac{1}{\langle 1,2 \rangle} & 0 & -\frac{1}{\langle 4,1 \rangle} \\ -\frac{1}{\langle 1,2 \rangle} & \frac{\langle 1,3 \rangle}{\langle 1,2 \rangle \langle 2,3 \rangle} & -\frac{1}{\langle 2,3 \rangle} & 0 \\ 0 & -\frac{1}{\langle 2,3 \rangle} & \frac{\langle 2,4 \rangle}{\langle 2,3 \rangle \langle 3,4 \rangle} & -\frac{1}{\langle 3,4 \rangle} \\ -\frac{1}{\langle 4,1 \rangle} & 0 & -\frac{1}{\langle 3,4 \rangle} & \frac{\langle 3,1 \rangle}{\langle 3,4 \rangle \langle 4,1 \rangle} \end{pmatrix} \begin{pmatrix} [\mu_1] \\ [\mu_2] \\ [\mu_3] \\ [\mu_4] \end{pmatrix}$$

Recap: Goal of Paper

The goal of the paper is to relate Grassmannian integral formulas written in 3 different formulations:

Twistor Space:

$$\tilde{\mathcal{L}}_{n;k}(\mathcal{W}) = \int \frac{d^{\tilde{k} \times n} B}{GL(\tilde{k})} \frac{\delta^{4\tilde{k}|4\tilde{k}}(B \cdot \mathcal{W})}{m_1 m_2 \dots m_n}.$$

Momentum Space:

$$\mathcal{L}_{n;k}(\lambda, \tilde{\lambda}, \tilde{\eta}) = \int \frac{d^{\tilde{k} \times n} B}{GL(\tilde{k})} \frac{\delta^{2\tilde{k}}(B_{\alpha i} \tilde{\lambda}_i) \delta^{2(n-\tilde{k})}(B_{\alpha i}^\perp \lambda_i) \delta^{(4\tilde{k})}(B_{\alpha i} \tilde{\eta}_{iA})}{m_1 m_2 \dots m_n},$$

Momentum Twistor Space:

$$\mathcal{L}_{n;k}(\mathcal{Z}) = \mathcal{A}_n^{\text{MHV}} \int \frac{d^{k \times n} C}{GL(k)} \frac{\delta^{4k|4k}(C \cdot \mathcal{Z})}{M_1 M_2 \dots M_n}.$$

For illustrative purposes, we do an example of how to actually compute something with the momentum twistor space Grassmannian integral formula:

$$\mathcal{L}_{n;k}(\mathcal{Z}) = \mathcal{A}_n^{\text{MHV}} \int \frac{d^{k \times n} C}{GL(k)} \frac{\delta^{4k|4k}(C \cdot \mathcal{Z})}{M_1 M_2 \cdots M_n}.$$

We do the simplest nontrivial case, which is NMHV. This means $k = 1$, so the formula is a contour integral in $Gr(1, n)$. Written explicitly, the elements are:

$$GL(1) \backslash C = GL(1) \backslash \begin{bmatrix} c_1 & c_2 & \cdots & c_n \end{bmatrix},$$

where c_i are complex numbers.

The Grassmannian integral is $\mathcal{L}_{n;1}(\mathcal{Z}) = \mathcal{A}_n^{\text{MHV}} \mathcal{I}_{n;1}(\mathcal{Z})$ with

$$\mathcal{I}_{n;1}^{(\Gamma)}(\mathcal{Z}) := \oint_{\Gamma} \frac{d^{1 \times n} C}{GL(1) c_1 c_2 \cdots c_n} \delta^4(c_i Z_i) \delta^{(4)}(c_i \eta_i).$$

The oriented volume form on $\mathbb{C}^n$ is $d^n C = \bigwedge_{i=1}^n dc^i$.

Since the bosonic delta function $\delta^4(c_i Z_i)$ fixes four c_i 's, and the $GL(1)$ redundancy fixes another, the integral is over $n - 5$ variables.

We suppose the contour Γ encircles a pole where exactly $n - 5$ of the c_i 's vanish. Such a contour can be characterized by specifying which five c_i 's are non-vanishing at the pole. Let us denote these five non-vanishing c_i 's by c_a, c_b, c_c, c_d , and c_e , and the corresponding contour γ_{abcde} . For example, if $n = 7$, we might have something like

$$\begin{bmatrix} c_a & 0 & c_b & c_c & c_d & c_e & 0 \end{bmatrix},$$

Thus, if we take the residue where all c_i vanish for $i \neq a, b, c, d, e$, this is, up to a sign (note: the only place where a c_i that we take the residue of shows up is in the delta functions, where they go to zero):

$$\mathcal{I}_{n;1}^{\gamma_{abcde}}(\mathcal{Z}) = \frac{\delta^4(c_a Z_a + c_b Z_b + c_c Z_c + c_d Z_d + c_e Z_e) \delta^{(4)}(c_a \eta_a + c_b \eta_b + c_c \eta_c + c_d \eta_d + c_e \eta_e)}{c_a c_b c_c c_d c_e}.$$

$$\mathcal{I}_{n;1}^{\gamma abcde}(\mathcal{Z}) = \frac{\delta^4(c_a Z_a + c_b Z_b + c_c Z_c + c_d Z_d + c_e Z_e) \delta^{(4)}(c_a \eta_a + c_b \eta_b + c_c \eta_c + c_d \eta_d + c_e \eta_e)}{c_a c_b c_c c_d c_e}.$$

Next, we use the 5-term Schouten identity (or Cramer's rule) that states that five 4-component vectors are necessarily linearly dependent:

$$\langle ijkl \rangle Z_m + \langle jklm \rangle Z_i + \langle klmi \rangle Z_j + \langle lmij \rangle Z_k + \langle mijk \rangle Z_l = 0.$$

The 4-brackets are the fully antisymmetric $SU(2,2)$ -invariants

$$\langle ijkl \rangle := -\epsilon_{ABCD} Z_i^A Z_j^B Z_k^C Z_l^D = \det(Z_i Z_j Z_k Z_l).$$

Note: we can prove the 5-term Schouten using the same method as for the 3-term Schouten.

Quiz: What does this imply the c_i 's are?

$$\mathcal{I}_{n;1}^{\gamma abcde}(\mathcal{Z}) = \frac{\delta^4(c_a Z_a + c_b Z_b + c_c Z_c + c_d Z_d + c_e Z_e) \delta^{(4)}(c_a \eta_a + c_b \eta_b + c_c \eta_c + c_d \eta_d + c_e \eta_e)}{c_a c_b c_c c_d c_e}.$$

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Note: we can prove the 5-term Schouten using the same method as for the 3-term Schouten.

Quiz: What does this imply the c_i 's are?

Answer: The constraint enforced by the bosonic delta-function is solved by

$$c_a = \langle bcde \rangle, \quad c_b = \langle cdea \rangle, \quad c_c = \langle deab \rangle, \quad c_d = \langle eabc \rangle, \quad c_e = \langle abcd \rangle,$$

Thus, the final answer is:

$$\mathcal{I}_{n;1}^{\gamma_{abcde}} = \frac{\delta^{(4)} \left(\langle bcde \rangle \eta_a + \langle cdea \rangle \eta_b + \langle deab \rangle \eta_c + \langle eabc \rangle \eta_d + \langle abcd \rangle \eta_e \right)}{\langle bcde \rangle \langle cdea \rangle \langle deab \rangle \langle eabc \rangle \langle abcd \rangle} =: [abcde],$$

or:

$$\mathcal{L}_{n;1}^{\gamma_{abcde}} = \mathcal{A}_n^{\text{MHV}} [abcde],$$

We recognize these 5-brackets that are the building blocks of NMHV amplitudes. If we only consider 5-brackets of the form $[i, j-1, j, k-1, k] := R_{ijk}$, these are the R-invariants that you get from calculating the NMHV amplitude using super-BCFW.

For example, $\mathcal{A}_6^{\text{NMHV}} = \mathcal{A}_6^{\text{MHV}} (R_{135} + R_{136} + R_{146})$.

In general, the formula is:

$$\mathcal{A}_n^{\text{NMHV}} = \mathcal{A}_n^{\text{MHV}} \sum_{j=2}^{n-3} \sum_{k=j+2}^{n-1} R_{nj k}$$

First, let's discuss how to go from Twistor Space:

$$\tilde{\mathcal{L}}_{n;k}(\mathcal{W}) = \int \frac{d^{\tilde{k} \times n} B}{GL(\tilde{k})} \frac{\delta^{4\tilde{k}|4\tilde{k}}(B \cdot \mathcal{W})}{m_1 m_2 \dots m_n}.$$

to Momentum Space:

$$\mathcal{L}_{n;k}(\lambda, \tilde{\lambda}, \tilde{\eta}) = \int \frac{d^{\tilde{k} \times n} B}{GL(\tilde{k})} \frac{\delta^{2\tilde{k}}(B_{\alpha i} \tilde{\lambda}_i) \delta^{2(n-\tilde{k})}(B_{\alpha i}^\perp \lambda_i) \delta^{(4\tilde{k})}(B_{\alpha i} \tilde{\eta}_{iA})}{m_1 m_2 \dots m_n},$$

Recall that twistor space is obtained from momentum space via a Fourier transform of λ_j , formally via

$$\int d^2 \lambda_j \exp(-i \tilde{\mu}_j^a \lambda_{ja}) \bullet,$$

for each $j = 1, 2, \dots, n$.

Thus, all we need to do is to do the inverse Fourier transform on all the $\tilde{\mu}_i$'s:

$$\mathcal{L}_{n;k}(\lambda, \tilde{\lambda}, \tilde{\eta}) = \left(\prod_{i=1}^n \int d^2 \tilde{\mu}_i e^{i \lambda_i \cdot \tilde{\mu}_i} \right) \tilde{\mathcal{L}}_{n;k}(\mathcal{W}).$$

Let's write out $\tilde{\mathcal{L}}_{n;k}(\mathcal{W})$ a bit more explicitly:

$$\begin{aligned}\tilde{\mathcal{L}}_{n;k}(\mathcal{W}) &= \int \frac{d^{\tilde{k} \times n} B}{GL(\tilde{k})} \frac{\delta^{4\tilde{k}|4\tilde{k}}(B \cdot \mathcal{W})}{m_1 m_2 \dots m_n} \\ &= \int \frac{d^{\tilde{k} \times n} B}{GL(\tilde{k})} \frac{\prod_{\alpha=1}^{\tilde{k}} \delta^4(\sum_i B_{\alpha i} W_i) \delta^{(4)}(\sum_i B_{\alpha i} \tilde{\eta}_i)}{m_1 m_2 \dots m_n} \\ &= \int \frac{d^{\tilde{k} \times n} B}{GL(\tilde{k})} \frac{\delta^{2\tilde{k}}(\sum_i B_{\alpha i} \tilde{\lambda}_i) \delta^{2\tilde{k}}(\sum_i B_{\alpha i} \tilde{\mu}_i) \delta^{(4\tilde{k})}(\sum_i B_{\alpha i} \tilde{\eta}_i)}{m_1 m_2 \dots m_n}\end{aligned}$$

and let's compare side-by-side with:

$$\mathcal{L}_{n;k}(\lambda, \tilde{\lambda}, \tilde{\eta}) = \int \frac{d^{\tilde{k} \times n} B}{GL(\tilde{k})} \frac{\delta^{2\tilde{k}}(B_{\alpha i} \tilde{\lambda}_i) \delta^{2(n-\tilde{k})}(B_{\alpha i}^\perp \lambda_i) \delta^{(4\tilde{k})}(B_{\alpha i} \tilde{\eta}_{iA})}{m_1 m_2 \dots m_n},$$

Rewriting, we want to calculate

$$\left(\prod_{i=1}^n \int d^2 \tilde{\mu}_i e^{i \lambda_i \cdot \tilde{\mu}_i} \right) \int \frac{d^{\tilde{k} \times n} B}{GL(\tilde{k})} \frac{\delta^{2\tilde{k}}(\sum_i B_{\alpha i} \tilde{\lambda}_i) \delta^{2\tilde{k}}(\sum_i B_{\alpha i} \tilde{\mu}_i) \delta^{(4\tilde{k})}(\sum_i B_{\alpha i} \tilde{\eta}_i)}{m_1 m_2 \dots m_n}$$

so we can focus on the $\tilde{\mu}$ -dependent **red** part:

Exercise: Do the inverse Fourier transform of the part in red.

The trick is to rewrite $\delta^{2\tilde{k}}(\sum_i B_{\alpha i} \tilde{\mu}_i)$ using the fact that this says $\tilde{\mu} \perp B$, but this is equivalent to saying: $\tilde{\mu} \subseteq B^\perp$.

Quiz: How do we find $B^\perp$ from B ? Suppose we have use the $GL(2)$ redundancy to set $B \in Gr(2, 5)$ to be of the form:

$$B = \begin{pmatrix} 1 & 0 & b_{13} & b_{14} & b_{15} \\ 0 & 1 & b_{23} & b_{24} & b_{25} \end{pmatrix}$$

What's $B^\perp$?

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Answer:

$$B^\perp = (-B^T \quad Id) = \begin{pmatrix} -b_{13} & -b_{23} & 1 & 0 & 0 \\ -b_{14} & -b_{24} & 0 & 1 & 0 \\ -b_{15} & -b_{25} & 0 & 0 & 1 \end{pmatrix}$$

Exercise: In order to solve the previous exercise, use

$$\delta^{2\tilde{k}}(B_{\alpha i} \tilde{\mu}_i) = \int d^{2(n-\tilde{k})} \sigma_{\bar{\alpha}} \delta^{2n}(\tilde{\mu}_i - \sigma_{\bar{\alpha}} B_{\bar{\alpha} i}^\perp),$$

Show that this formula is true in the case of B above. Doing this will be helpful for understanding the dimensions of the objects we are dealing with.

Answer to 2nd exercise

The delta function is $\delta^{2\tilde{k}}(B_{\alpha i} \tilde{\mu}_i)$.

The 2 comes from the fact that each $\tilde{\mu}_i$ has 2 components, which we call x and y: $\tilde{\mu}_i = \begin{pmatrix} \tilde{\mu}_i^x \\ \tilde{\mu}_i^y \end{pmatrix}$. With our choice of gauge above, we have:

$$\delta^{2\tilde{k}}(B_{\alpha i} \tilde{\mu}_i) \Leftrightarrow \begin{cases} \tilde{\mu}_1 + b_{13}\tilde{\mu}_3 + b_{14}\tilde{\mu}_4 + b_{15}\tilde{\mu}_5 \\ \tilde{\mu}_2 + b_{23}\tilde{\mu}_3 + b_{24}\tilde{\mu}_4 + b_{25}\tilde{\mu}_5 \end{cases}$$

This is of course 4 equations because we have $\tilde{\mu}_i^x$ and $\tilde{\mu}_i^y$ as noted above.

Let's show $\delta^{2\tilde{k}}(B_{\alpha i} \tilde{\mu}_i) = \int d^{2(n-\tilde{k})} \sigma_{\tilde{\alpha}} \delta^{2n}(\tilde{\mu}_i - \sigma_{\tilde{\alpha}} B_{\tilde{\alpha} i}^\perp)$, by evaluating against $\int d^{2\tilde{k}} \tilde{\mu} f(\tilde{\mu}_1, \tilde{\mu}_2, \tilde{\mu}_3, \tilde{\mu}_4, \tilde{\mu}_5)$:

$$\int d\tilde{\mu}_1 d\tilde{\mu}_2 \delta^{2\tilde{k}}(B_{\alpha i} \tilde{\mu}_i) f(\tilde{\mu}_1, \tilde{\mu}_2, \tilde{\mu}_3, \tilde{\mu}_4, \tilde{\mu}_5)$$

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This is of course 4 equations because we have $\tilde{\mu}_i^x$ and $\tilde{\mu}_i^y$ as noted above.

Let's show $\delta^{2\tilde{k}}(B_{\alpha i} \tilde{\mu}_i) = \int d^{2(n-\tilde{k})} \sigma_{\tilde{\alpha}} \delta^{2n}(\tilde{\mu}_i - \sigma_{\tilde{\alpha}} B_{\tilde{\alpha} i}^{\perp})$, by evaluating against $\int d^{2\tilde{k}} \tilde{\mu} f(\tilde{\mu}_1, \tilde{\mu}_2, \tilde{\mu}_3, \tilde{\mu}_4, \tilde{\mu}_5)$:

$$\begin{aligned} & \int d\tilde{\mu}_1 d\tilde{\mu}_2 \delta^{2\tilde{k}}(B_{\alpha i} \tilde{\mu}_i) f(\tilde{\mu}_1, \tilde{\mu}_2, \tilde{\mu}_3, \tilde{\mu}_4, \tilde{\mu}_5) \\ &= f(-b_{13}\tilde{\mu}_3 - b_{14}\tilde{\mu}_4 - b_{15}\tilde{\mu}_5, -b_{23}\tilde{\mu}_3 - b_{24}\tilde{\mu}_4 - b_{25}\tilde{\mu}_5, \tilde{\mu}_3, \tilde{\mu}_4, \tilde{\mu}_5), \text{ where we simply substituted using the equations above.} \end{aligned}$$

Now let's evaluate the other side:

$$\int d\tilde{\mu}_1 d\tilde{\mu}_2 \int d^{2(n-\tilde{k})} \sigma_{\tilde{\alpha}} \delta^{2n}(\tilde{\mu}_i - \sigma_{\tilde{\alpha}} B_{\tilde{\alpha} i}^{\perp}) f(\tilde{\mu}_1, \tilde{\mu}_2, \tilde{\mu}_3, \tilde{\mu}_4, \tilde{\mu}_5)$$

Note that: $\delta^{2n}(\tilde{\mu}_i - \sigma_{\tilde{\alpha}} B_{\tilde{\alpha} i}^{\perp}) =$

$$\delta\left(\tilde{\mu}_1 - \sigma_1(-b_{13}) - \sigma_2(-b_{14}) - \sigma_3(-b_{15})\right) \delta\left(\tilde{\mu}_2 - \sigma_1(-b_{23}) - \sigma_2(-b_{24}) - \sigma_3(-b_{25})\right) \delta(\tilde{\mu}_3 - \sigma_1) \delta(\tilde{\mu}_4 - \sigma_2) \delta(\tilde{\mu}_5 - \sigma_3)$$

Then:

$$\int d\tilde{\mu}_1 d\tilde{\mu}_2 \int d^6 \sigma_{\tilde{\alpha}} \delta\left(\tilde{\mu}_1 + b_{13}\sigma_1 + b_{14}\sigma_2 + b_{15}\sigma_3\right) \delta\left(\tilde{\mu}_2 + b_{23}\sigma_1 + b_{24}\sigma_2 + b_{25}\sigma_3\right) \delta(\tilde{\mu}_3 - \sigma_1) \delta(\tilde{\mu}_4 - \sigma_2) \delta(\tilde{\mu}_5 - \sigma_3) f(\tilde{\mu}_1, \tilde{\mu}_2, \tilde{\mu}_3, \tilde{\mu}_4, \tilde{\mu}_5)$$

$$= \int d^6 \sigma_{\tilde{\alpha}} \delta(\tilde{\mu}_3 - \sigma_1) \delta(\tilde{\mu}_4 - \sigma_2) \delta(\tilde{\mu}_5 - \sigma_3) f(-b_{13}\sigma_1 - b_{14}\sigma_2 - b_{15}\sigma_3, -b_{23}\sigma_1 - b_{24}\sigma_2 - b_{25}\sigma_3, \tilde{\mu}_3, \tilde{\mu}_4, \tilde{\mu}_5)$$

$$= f(-b_{13}\tilde{\mu}_3 - b_{14}\tilde{\mu}_4 - b_{15}\tilde{\mu}_5, -b_{23}\tilde{\mu}_3 - b_{24}\tilde{\mu}_4 - b_{25}\tilde{\mu}_5, \tilde{\mu}_3, \tilde{\mu}_4, \tilde{\mu}_5)$$

Answer to 1st exercise

Coming back to the calculation of:

$$\left(\prod_{i=1}^n \int d^2 \tilde{\mu}_i e^{i \lambda_i \cdot \tilde{\mu}_i} \right) \delta^{2\tilde{k}} \left(\sum_i B_{\alpha i} \tilde{\mu}_i \right)$$

Using our previous exercise/trick to rewrite this as:

$$\left(\prod_{i=1}^n \int d^2 \tilde{\mu}_i e^{i \lambda_i \cdot \tilde{\mu}_i} \right) \int d^{2(n-\tilde{k})} \sigma_{\tilde{\alpha}} \delta^{2n} (\tilde{\mu}_i - \sigma_{\tilde{\alpha}} B_{\tilde{\alpha} i}^{\perp}),$$

and furthermore rewriting

$$\delta^{2n} (\tilde{\mu}_i - \sigma_{\tilde{\alpha}} B_{\tilde{\alpha} i}^{\perp}) = \prod_{i=1}^n \int d^2 \tau_i e^{-i \tau_i (\tilde{\mu}_i - \sigma_{\tilde{\alpha}} B_{\tilde{\alpha} i}^{\perp})}$$

we get:

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we get:

$$\begin{aligned} & \prod_{i=1}^n \int d^2 \tau_i \int d^{2(n-\tilde{k})} \sigma_{\tilde{\alpha}} \left(\int d^2 \tilde{\mu}_i e^{i (\lambda_i - \tau_i) \cdot \tilde{\mu}_i} \right) e^{i \tau_i \sigma_{\tilde{\alpha}} B_{\tilde{\alpha} i}^{\perp}} \\ &= \prod_{i=1}^n \int d^2 \tau_i \int d^{2(n-\tilde{k})} \sigma_{\tilde{\alpha}} \left(\delta^{2n} (\lambda_i - \tau_i) \right) e^{i \tau_i \sigma_{\tilde{\alpha}} B_{\tilde{\alpha} i}^{\perp}} \\ &= \prod_{i=1}^n \int d^{2(n-\tilde{k})} \sigma_{\tilde{\alpha}} e^{i \lambda_i \sigma_{\tilde{\alpha}} B_{\tilde{\alpha} i}^{\perp}} \\ &= \prod_{i=1}^n \delta^{2(n-\tilde{k})} (\lambda_i B_{\tilde{\alpha} i}^{\perp}) \end{aligned}$$

which is exactly what we needed to show

Now that we have obtained the Momentum Space version:

$$\mathcal{L}_{n;k}(\lambda, \tilde{\lambda}, \tilde{\eta}) = \int \frac{d^{\tilde{k} \times n} B}{GL(\tilde{k})} \frac{\delta^{2\tilde{k}}(B_{\alpha i} \tilde{\lambda}_i) \delta^{2(n-\tilde{k})}(B_{\alpha i}^{\perp} \lambda_i) \delta^{(4\tilde{k})}(B_{\alpha i} \tilde{\eta}_{iA})}{m_1 m_2 \cdots m_n},$$

our final step is to get to the Momentum Twistor Space version:

$$\begin{aligned} \mathcal{L}_{n;k}(\mathcal{Z}) &= \mathcal{A}_n^{\text{MHV}} \int \frac{d^{k \times n} C}{GL(k)} \frac{\delta^{4k|4k}(C \cdot \mathcal{Z})}{M_1 M_2 \cdots M_n} \\ &= \mathcal{A}_n^{\text{MHV}} \int \frac{d^{k \times n} C_{\hat{\alpha} i}}{GL(k)} \frac{\delta^{2k}(C_{\hat{\alpha} i} \lambda_i) \delta^{2k}(C_{\hat{\alpha} i} \mu_i) \delta^{(4k)}(C_{\hat{\alpha} i} \eta_i)}{M_1 M_2 \cdots M_n} \end{aligned}$$

Overview

This is a somewhat involved calculation. Here are the main steps:

- reduce the integral from $\text{Gr}(k+2,n)$ to $\text{Gr}(k,n)$
- change to momentum twistor space
- fix translational redundancy
- change variables from B to C

In order to reduce the Grassmannian by dimension 2, we start by taking the bosonic delta functions $\delta^{2(n-\tilde{k})}(B^\perp \cdot \lambda)$; these require that the λ 2-plane lies in the orthogonal complement of $B^\perp$, so using the same trick as above, we rewrite it as:

$$\prod_{\beta=1}^{\tilde{k}} \int d^2 \rho_\beta \delta^{2n}(\lambda_j - \rho_\alpha B_{\alpha j}),$$

where ρ_α^a is a $2 \times \tilde{k}$ array of dummy integration variables.

We can use 2 dimensions of the $GL(k+2)$ to fix 2 dimensions/rows of the B-matrix, or equivalently (I don't have a proof) we can fix the $2 \times \tilde{k}$ array of ρ variables.

Exercise: What happens to the B-matrix if you set $\rho = \begin{pmatrix} 0 & \cdots & 0 & 1 & 0 \\ 0 & \cdots & 0 & 0 & 1 \end{pmatrix}$?

Do an example with 3 columns ($\tilde{k} = 3$), so $\rho = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$, and $n = 3$. Given this change to the B-matrix, rewrite the $\mathcal{L}_{n;k}(\lambda, \tilde{\lambda}, \tilde{\eta})$ integral in the new form.

Answer: The $2n$ delta functions then fix the last two rows of B to be the λ 's:

$$B = \begin{pmatrix} B_{11} & B_{12} & \cdots & B_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ B_{k1} & B_{k2} & \cdots & B_{kn} \\ \lambda_1^1 & \lambda_2^1 & \cdots & \lambda_n^1 \\ \lambda_1^2 & \lambda_2^2 & \cdots & \lambda_n^2 \end{pmatrix}.$$

For the three-column example (so $\tilde{k} = 3$) with $n = 3$, $B = \begin{pmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{31} & b_{32} & b_{33} \end{pmatrix}$

Then $\delta^{2n}(\lambda_j - \rho_\alpha B_{\alpha j}) = \delta^2(\lambda_1 - \rho_1 b_{11} - \rho_2 b_{21} - \rho_3 b_{31}) \delta^2(\lambda_2 - \rho_1 b_{12} - \rho_2 b_{22} - \rho_3 b_{32}) \delta^2(\lambda_3 - \rho_1 b_{13} - \rho_2 b_{23} - \rho_3 b_{33})$

where the 2's are because there are both x and y components. Writing them explicitly, while also substituting in the values for ρ we fixed above (either 0 or 1), we get:

$$\delta(\lambda_1^x - b_{21}) \delta(\lambda_1^y - b_{31}) \delta(\lambda_2^x - b_{22}) \delta(\lambda_2^y - b_{32}) \delta(\lambda_3^x - b_{23}) \delta(\lambda_3^y - b_{33})$$

This just sets $B = \begin{pmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{31} & b_{32} & b_{33} \end{pmatrix} \mapsto \begin{pmatrix} b_{11} & b_{12} & b_{13} \\ \lambda_1^x & \lambda_2^x & \lambda_3^x \\ \lambda_1^y & \lambda_2^y & \lambda_3^y \end{pmatrix}$

This determines the $\delta^{2(n-\tilde{k})}(B^\perp \cdot \lambda)$ delta functions. To see what happens to the other delta functions, we realize that only the last 2 rows of B change, so we can separate out these delta functions.

For these, we find that the last two rows of $\delta^{2\tilde{k}}(B_{\alpha i} \tilde{\lambda}_i) \delta^{(4\tilde{k})}(B_{\alpha i} \tilde{\eta}_{iA})$ simply give momentum conservation and supermomentum conservation.

Thus, after evaluating the ρ integrals, we find

$$\mathcal{L}_{n;k}(\lambda, \tilde{\lambda}, \tilde{\eta}) = \delta^4(\lambda_i \tilde{\lambda}_i) \delta^{(8)}(\lambda_i \tilde{\eta}_i) \times \int \frac{d^{k \times n} B_{\hat{\alpha} i}}{GL(k) \ltimes T_k} \frac{\delta^{2k}(B_{\hat{\alpha} i} \tilde{\lambda}_i) \delta^{(4k)}(B_{\hat{\alpha} i} \tilde{\eta}_i)}{m_1 m_2 \cdots m_n},$$

with $\hat{\alpha} = 1, 2, \dots, k$.

T_k indicates the translational redundancy in the $B_{\hat{\alpha}i}$ -variables. The translational symmetry acts as

$$B_{\hat{\alpha}i} \rightarrow B_{\hat{\alpha}i} + r_{x\hat{\alpha}}\lambda_i^x + r_{y\hat{\alpha}}\lambda_i^y \quad \text{for all } i \text{ simultaneously,}$$

where $r_{1\hat{\alpha}}$ and $r_{2\hat{\alpha}}$ are any numbers.

Exercise: Show that this leaves the integral unchanged.

Answer: This is a mixing of the last two rows in the B -matrix with the other rows, and this leaves the minors m_i unchanged. It is also clear that on the support of the two delta functions $\delta^4(\lambda_i \tilde{\lambda}_i) \delta^{(8)}(\lambda_i \tilde{\eta}_i)$ (that encode momentum and supermomentum conservation), the delta-functions in the integral are invariant under such a shift.

In detail, if we look at: $\delta^{2k}(B_{\hat{\alpha}i} \tilde{\lambda}_i) \delta^{(4k)}(B_{\hat{\alpha}i} \tilde{\eta}_i)$, or just one of the terms of the first one (the others are analogous), we find that

$$B_{\hat{\alpha}1} \tilde{\lambda}_1 + B_{\hat{\alpha}2} \tilde{\lambda}_2 + \cdots + B_{\hat{\alpha}n} \tilde{\lambda}_n = 0$$

$\mapsto$

$$\begin{aligned} & (B_{\hat{\alpha}1} + r_{x\hat{\alpha}} \lambda_1^x + r_{y\hat{\alpha}} \lambda_1^y) \tilde{\lambda}_1 + (B_{\hat{\alpha}2} + r_{x\hat{\alpha}} \lambda_2^x + r_{y\hat{\alpha}} \lambda_2^y) \tilde{\lambda}_2 + \cdots + (B_{\hat{\alpha}n} + r_{x\hat{\alpha}} \lambda_n^x + r_{y\hat{\alpha}} \lambda_n^y) \tilde{\lambda}_n \\ &= B_{\hat{\alpha}1} \tilde{\lambda}_1 + B_{\hat{\alpha}2} \tilde{\lambda}_2 + \cdots + B_{\hat{\alpha}n} \tilde{\lambda}_n + r_{x\hat{\alpha}} (\lambda_1^x \tilde{\lambda}_1 + \lambda_2^x \tilde{\lambda}_2 + \cdots + \lambda_n^x \tilde{\lambda}_n) + \\ & r_{y\hat{\alpha}} (\lambda_1^y \tilde{\lambda}_1 + \lambda_2^y \tilde{\lambda}_2 + \cdots + \lambda_n^y \tilde{\lambda}_n), \end{aligned}$$

and the latter two terms are zero since $\lambda^a \tilde{\lambda}^b = 0$ for $a, b = 1, 2$ by momentum conservation.

We change variables in the external data to go from momentum space to momentum twistor space. The momentum supertwistors $\mathcal{Z}_i = (\lambda_i, \mu_i | \eta_i)$ are related to the momentum space variables via the relations we gave at the beginning for the formula of $[i]$. Using these relations, we directly find for each $\hat{\alpha} = 1, 2, \dots, k$:

$$\sum_{i=1}^n B_{\hat{\alpha}i} \tilde{\lambda}_i = - \sum_{i=1}^n C_{\hat{\alpha}i} \mu_i, \quad \sum_{i=1}^n B_{\hat{\alpha}i} \tilde{\eta}_i = - \sum_{i=1}^n C_{\hat{\alpha}i} \eta_i,$$

Exercise: find what the $C_{\hat{\alpha}i}$ are equal to.

Answer:

$C_{\hat{\alpha}i}$ is the coefficient of μ_i . If, in $\sum_{i=1}^n B_{\hat{\alpha}i} \tilde{\lambda}_i$ we look at $B_{\hat{\alpha}i}[i|]$, this is equal to, by the formula for $[i|]$:

$$B_{\hat{\alpha}i} \left(\frac{\langle i, i+1 \rangle [\mu_{i-1}|] + \langle i-1, i \rangle [\mu_{i+1}|] + \langle i+1, i-1 \rangle [\mu_i|]}{\langle i-1, i \rangle \langle i, i+1 \rangle} \right), \text{ and the piece with } [\mu_i| \text{ is } \\ \frac{B_{\hat{\alpha},i} \langle i+1, i-1 \rangle}{\langle i-1, i \rangle \langle i, i+1 \rangle}.$$

The only other terms with a $[\mu_i|$ are from $[i-1|$ and $[i+1|$, so we if look at these three terms summed together:

$$\left(\frac{B_{\hat{\alpha},i-1} \langle i-2, i-1 \rangle}{\langle i-2, i-1 \rangle \langle i-1, i \rangle} + \frac{B_{\hat{\alpha},i} \langle i+1, i-1 \rangle}{\langle i-1, i \rangle \langle i, i+1 \rangle} + \frac{B_{\hat{\alpha},i+1} \langle i+1, i+2 \rangle}{\langle i, i+1 \rangle \langle i+1, i+2 \rangle} \right) [\mu_i|$$

Thus,

$$C_{\hat{\alpha}i} = \frac{\langle i, i+1 \rangle B_{\hat{\alpha},i-1} + \langle i-1, i \rangle B_{\hat{\alpha},i+1} + \langle i+1, i-1 \rangle B_{\hat{\alpha}i}}{\langle i-1, i \rangle \langle i, i+1 \rangle}.$$

Using a trick of Arkani-Hamed, Cachazo, and Cheung, we can rewrite the $(k+2) \times (k+2)$ minors m_i of the B -matrix in terms of the $k \times k$ minors of the C -matrix as

$$m_1 = (B_1 \dots B_{k+2}) = -\langle 12 \dots \langle k+1, k+2 (C_2 \dots C_{k+1}) \quad \text{etc.}$$

Defining the $k \times k$ minors of the $k \times n$ C -matrix to be $M_1 := (C_1 \dots C_k)$ etc, we thus have

$$m_1 m_2 \dots m_n = (-1)^n (\langle 12 \rangle \langle 23 \rangle \dots \langle n1 \rangle)^{k+1} M_1 M_2 \dots M_n.$$

(We drop the signs $(-1)^n$ just as we drop 2π 's in the Fourier transforms.) Thus, we now have

$$\mathcal{L}_{n;k}(\lambda, \tilde{\lambda}, \tilde{\eta}) = \frac{\delta^4(\lambda_i \tilde{\lambda}_i) \delta^{(8)}(\lambda_i \tilde{\eta}_i)}{(\langle 12 \rangle \langle 23 \rangle \dots \langle 1n \rangle)^{k+1}} \int \frac{d^{k \times n} B_{\hat{\alpha}i}}{GL(k) \rtimes T_k} \frac{\delta^{2k}(C_{\hat{\alpha}i} \mu_i) \delta^{(4k)}(C_{\hat{\alpha}i} \eta_i)}{M_1 M_2 \dots M_n}.$$

It is here understood that the C 's are functions of the B 's as given above.

Note that the Schouten identity guarantees the following two important properties:

- The C 's are invariant under the translations
$$B_{\hat{\alpha}i} \rightarrow B_{\hat{\alpha}i} + r_{1\hat{\alpha}}\lambda_i^1 + r_{2\hat{\alpha}}\lambda_i^2 \quad \text{for all } i \text{ simultaneously,}$$
- The expression for the C 's in terms of the B 's implies that $C_{\hat{\alpha}i}\lambda_i = 0$.

We would now like to do two things: fix the translational redundancy and rewrite the integral in terms of C 's instead of B 's.

Because of the translational invariance, the B 's are not independent variables: for example we can use translations to set $2k$ of them to zero (see below). So after fixing translational invariance, we will have $kn - 2k = k(n - 2)$ variables to integrate over.

Let us use the translation invariance T_k to fix the first two columns in $B_{\hat{\alpha}i}$ to be zero.

Exercise: How do we do this, and what is the result?

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Exercise: How do we do this, and what is the result?

Answer: This means that all $\hat{\alpha} = 1, \dots, k$ we set $B_{\hat{\alpha}1} = B_{\hat{\alpha}2} = 0$, explicitly:

$$B_{\hat{\alpha}1} \rightarrow B_{\hat{\alpha}1} + r_{x\hat{\alpha}}\lambda_1^x + r_{y\hat{\alpha}}\lambda_1^y = 0$$

$$B_{\hat{\alpha}2} \rightarrow B_{\hat{\alpha}2} + r_{x\hat{\alpha}}\lambda_2^x + r_{y\hat{\alpha}}\lambda_2^y = 0$$

If we solve this, we find that $r_{x\hat{\alpha}} = \frac{B_{\hat{\alpha}2}\lambda_1^y - B_{\hat{\alpha}1}\lambda_2^y}{\langle 12 \rangle}$, and $r_{y\hat{\alpha}} = \frac{B_{\hat{\alpha}1}\lambda_2^x - B_{\hat{\alpha}2}\lambda_1^x}{\langle 12 \rangle}$, and all $B_{\hat{\alpha}3}, B_{\hat{\alpha}4}, \dots$ stay the same.

This gives

$$\frac{d^{k \times n} B_{\hat{\alpha}i}}{T_k} = \langle 12 \rangle^k d^{k \times (n-2)} B_{\hat{\alpha}i},$$

where the included prefactor preserves the scaling properties of the measure. (This can be derived more carefully as a Jacobian of the gauge fixing.)

We know how $C_{\hat{\alpha}i}$ is related to $B_{\hat{\alpha}i}$ from above. We can use that relation to solve for $k(n-2)$ of the components of C in terms of the $k(n-2)$ unfixed components of B . Given our choice to set $B_{\hat{\alpha}1} = B_{\hat{\alpha}2} = 0$, we have the following system of $k(n-2)$ equations:

$$C_{\hat{\alpha}i} = \begin{cases} \frac{\langle i, i+1 \rangle B_{\hat{\alpha}, i-1} + \langle i+1, i-1 \rangle B_{\hat{\alpha}i} + \langle i-1, i \rangle B_{\hat{\alpha}, i+1}}{\langle i-1, i \rangle \langle i, i+1 \rangle} & \text{for } 3 < i < n \\ \frac{\langle 42 \rangle B_{\hat{\alpha}3} + \langle 23 \rangle B_{\hat{\alpha}4}}{\langle 23 \rangle \langle 34 \rangle} & \text{for } i = 3 \\ \frac{\langle n1 \rangle B_{\hat{\alpha}, n-1} + \langle 1, n-1 \rangle B_{\hat{\alpha}n}}{\langle n-1, n \rangle \langle n1 \rangle} & \text{for } i = n \end{cases}.$$

We can write this as $C_{\hat{\alpha}\hat{j}} = B_{\hat{\alpha}\hat{i}} Q_{\hat{i}\hat{j}}$, with $\hat{i}, \hat{j} = 3, \dots, n$, for a square symmetric matrix $Q_{\hat{i}\hat{j}}$ with nonzero entries only on and adjacent to the main diagonal. In their Appendix, they show that

$$|\det Q| = \frac{\langle 12 \rangle^2}{\langle 12 \rangle \langle 23 \rangle \cdots \langle n1 \rangle}.$$

Therefore the measure transforms as

$$d^{k(n-2)} B_{\hat{\alpha}\hat{i}} = \frac{d^{k(n-2)} C_{\hat{\alpha}\hat{i}}}{|\det Q|^k} = \left(\frac{\langle 12 \rangle \langle 23 \rangle \cdots \langle n1 \rangle}{\langle 12 \rangle^2} \right)^k d^{k(n-2)} C_{\hat{\alpha}\hat{i}}.$$

We take the absolute value of the determinant since the overall sign is irrelevant.

With these formulas, the integral now takes the form

$$\mathcal{L}_{n;k}(\mathcal{Z}) = \frac{\delta^4(\lambda_i \tilde{\lambda}_i) \delta^{(8)}(\lambda_i \tilde{\eta}_i)}{\langle 12 \rangle \langle 23 \rangle \cdots \langle 1n \rangle} \frac{1}{\langle 12 \rangle^k} \int \frac{d^{k \times (n-2)} C_{\hat{\alpha}i}}{GL(k)} \frac{\delta^{2k}(C_{\hat{\alpha}i} \mu_i) \delta^{(4k)}(C_{\hat{\alpha}i} \eta_i)}{M_1 M_2 \cdots M_n} \Big|_{C_{\hat{\alpha}1,2} = C_{\hat{\alpha}1,2}^{(0)}}.$$

We recognize the first factor as the MHV superamplitude $\mathcal{A}_n^{\text{MHV}}$.

The restriction of $C_{\hat{\alpha}1}$ and $C_{\hat{\alpha}2}$ follows from the relation between the B and C ; it was used above to solve for $k(n-2)$ components of C in terms of the B 's, but the remaining $2k$ components of C are then fixed as

$$C_{\hat{\alpha}1} = \frac{B_{\hat{\alpha}n}}{\langle n1 \rangle} = \sum_{j=3}^n \frac{\langle 2j \rangle}{\langle 12 \rangle} C_{\hat{\alpha}j} =: C_{\hat{\alpha}1}^{(0)}, \quad C_{\hat{\alpha}2} = \frac{B_{\hat{\alpha}3}}{\langle 23 \rangle} = - \sum_{j=3}^n \frac{\langle 1j \rangle}{\langle 12 \rangle} C_{\hat{\alpha}j} =: C_{\hat{\alpha}2}^{(0)}.$$

Thus, when evaluating the integral, $C_{\hat{\alpha}1}$ and $C_{\hat{\alpha}2}$ are functions of the other $k(n-2)$ C -components. This is a restriction of the region of integration that we can also impose via $2k$ delta functions $\delta(C_{\hat{\alpha}i} - C_{\hat{\alpha}i}^{(0)})$ for $i = 1, 2$. Moreover, it follows from the explicit solution in the previous equation that the constraints are equivalent to $C_{\hat{\alpha}i}\lambda_i = 0$. Thus we can rewrite the delta function restriction as

$$\delta(C_{\hat{\alpha}1} - C_{\hat{\alpha}1}^{(0)}) \delta(C_{\hat{\alpha}2} - C_{\hat{\alpha}2}^{(0)}) = \langle 12 \delta^2(C_{\hat{\alpha}i}\lambda_i) .$$

for each $\hat{\alpha} = 1, 2, \dots, k$.

We then have

$$\mathcal{L}_{n;k}(\mathcal{Z}) = \mathcal{A}_n^{\text{MHV}} \int \frac{d^{k \times n} C_{\hat{\alpha}i}}{GL(k)} \frac{\delta^{2k}(C_{\hat{\alpha}i}\lambda_i) \delta^{2k}(C_{\hat{\alpha}i}\mu_i) \delta^{(4k)}(C_{\hat{\alpha}i}\eta_i)}{M_1 M_2 \cdots M_n}.$$

Although we chose to fix the first two columns of B to be zero, the answer is independent of that choice; the factors of $\langle 12 \rangle$ cancel out. We can now write the result directly in terms of the momentum supertwistors

$\mathcal{Z}_i = (Z_i | \eta_i) = (\lambda_i, \mu_i | \eta_i)$ as

$$\mathcal{L}_{n;k}(\mathcal{Z}) = \mathcal{A}_n^{\text{MHV}} \int \frac{d^{k \times n} C_{\hat{\alpha}i}}{GL(k)} \frac{\delta^{4k}(C_{\hat{\alpha}i}Z_i) \delta^{(4k)}(C_{\hat{\alpha}i}\eta_i)}{M_1 M_2 \cdots M_n} = \mathcal{A}_n^{\text{MHV}} \int \frac{d^{k \times n} C_{\hat{\alpha}i}}{GL(k)} \frac{\delta^{4k}(C_{\hat{\alpha}i}Z_i) \delta^{(4k)}(C_{\hat{\alpha}i}\eta_i)}{M_1 M_2 \cdots M_n}.$$

This completes our derivation of the $\mathcal{N} = 4$ SYM Grassmannian integral in momentum twistor space from that in momentum space.